

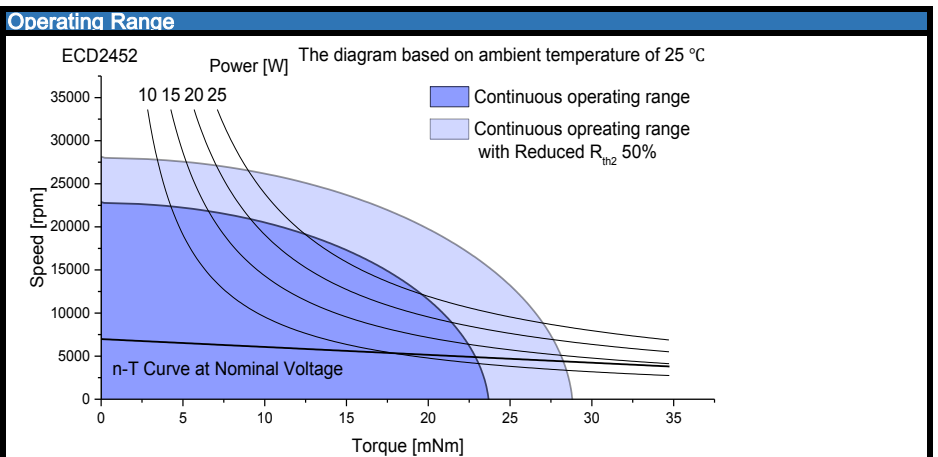
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With hall sensor	ECD2452S-...	1207	2407						
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Motor data									
1	Nominal voltage	V	12	24					
2	No load speed	rpm	7080	6980					
3	No load current	mA	103	68					
4	Nominal speed	rpm	5941	5834					
5	Nominal torque	mNm	14	14					
6	Nominal current	A	0,98	0,51					
7	Stall torque	mNm	87	85,2					
8	Stall current	A	5,58	2,73					
9	Max. efficiency	%	74,7	70,9					

10	Supply voltage +Vcc	V	10..28	10..28					
11	Direction of rotation		CW	CW					
12	Torque constant	mNm/A	15,9	32					
13	Speed constant	rpm/V	601	298					
14	Speed/torque gradient	rpm/mNm	81,3	81,9					
15	Mechanical time constant	ms	3,6	3,6					
16	Rotor inertia	gcm ²	4,2	4,2					

17	Thermal resistance housing-ambient	11.6 K/W
18	Thermal resistance winding-housing	5.6 K/W
19	Thermal time constant winding	30 s
20	Thermal time constant motor	557 s
21	Ambient temperature	-40...+100°C
22	Max. permissible winding temperature	+150°C
23	Max. permissible speed	30000 rpm
24	Axial play at axial load	<4 N 0 mm >4 N max. 0.3 mm
25	Radial play	preloaded
26	Max. axial load (dynamic)	3.5 N
27	Max. force for press fits (static)	44 N
	(static, shaft supported)	1200 N
28	Max. radial loading, 5mm from flange	15 N
29	Number of pole pairs	1
30	Number of phases	3
31	Weight of motor	112 g



Controller features	
Sensor, Open loop, $I_{max} < 1.5A$	
Overload protection, Stall protection	
Max. temperature of electronics	+105°C

Configuration	
Function:	On&Off/Direction/Speed control/Brake
Speed control:	Speed closed&open-loop Control/Speed feedback
Performance:	Customized in the continuous operating range
Ball bearing:	Preload
Flange:	Standard frange front&back/customize the frange
Shaft:	Length/Diameter/Cut face
Leadwire:	PVC/Silicon/Teflon/UL No/Dimension/length
Connector:	JST/MOLEX/TE

Connection	
Connection	PTFE
Pin 1 +VCC	AWG24 red
Pin 2 GND	AWG24 black

Caution:
Incorrect lead connection will damage the controller!

More :
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